

Advanced Macroeconomics 1

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Lecture 3:
Neoclassical Growth, an introduction

Ramsey model in discrete time (ref:

Heer and Maussner, ch 1)

- How much should a country save (Ramsey, 1928)?
- Like the Sollow model but with an endogenous saving rate.
- The most basic DGE model.
- The core of many macroeconomic models.
- Also known as the Ramsey-Cass-Koopmans model or the neoclassical growth model.
- We start with a finite-time version with a constant labor force and no technological growth.
- Let's focus on the planner's problem where the planner maximizes the utility of the representative household

- Time t is divided into intervals of unit length and extends from $t=0$ to $t=T$.
- The production function $F(N_t, K_t)$ has the usual properties
 - $F(N, 0) = 0$
 - F is strictly increasing in both of its arguments
 - concave
 - twice continuously differentiable
- The representative agent does not value leisure and seeks to maximize utility function

$$U(C_0, C_1, \dots, C_T) \tag{1}$$

- The economy's resource constraint is given by

$$Y_t + (1 - \delta)K_t \geq C_t + K_{t+1}, \tag{2}$$

where $0 < \delta < 1$.

- We can simplify the notation

$$f(K_t) \equiv F(N, K_t) + (1 - \delta)K_t \quad (3)$$

- The planner's problem is given by

$$\begin{aligned} & \max_{\{C_0, \dots, C_T, K_1, \dots, K_{T+1}\}} U(C_0, C_1, \dots, C_T) \\ & \quad K_{t+1} + C_t \leq f(K_t) \\ \text{st} \quad & \quad 0 \leq C_t \quad , \\ & \quad 0 \leq K_{t+1} \\ & \quad \text{for all } t = 0, \dots, T \end{aligned}$$

where K_0 is given.

- This is a standard non-linear programming problem and thus we can apply the Kuhn-Tucker theorem ($U(\cdot)$ and $f(\cdot)$ are strictly concave, strictly increasing and twice differentiable).
- To proceed, let's write the following Lagrangian:

$$\mathcal{L} = U(C_0, \dots, C_T) + \sum_{t=0}^T [\lambda_t(f(K_t) - C_t - K_{t+1}) + \mu_t C_t + \omega_{t+1} K_{t+1}]$$

- NB: ω_t are just Lagrangean multipliers here (not the endowments as they were in the previous lecture).

- We get the following FOCs

$$\begin{aligned} \frac{\partial U(\cdot)}{\partial C_t} - \lambda_t + \mu_t &= 0 & t = 0, \dots, T \\ -\lambda_t + \lambda_{t+1}f'(K_{t+1}) + \omega_{t+1} &= 0 & t = 0, \dots, T-1 \\ -\lambda_T + \omega_{T+1} &= 0 \\ \lambda_t(f(K_t) - C_t - K_{t+1}) &= 0 & t = 0, \dots, T \\ \mu_t C_t &= 0 & t = 0, \dots, T \\ \omega_{t+1} K_{t+1} &= 0 & t = 0, \dots, T, \end{aligned}$$

where $\lambda_t \geq 0, \mu_t \geq 0, \omega_t \geq 0$ for all t .

- As usually, the multipliers value the severeness of the respective constraint (the 'shadow price').
- A constraint that does not bind has a multiplier zero.

- We can use the Inada conditions, $\frac{\partial U(\cdot)}{\partial C_t} \rightarrow \infty$ when $C_t \rightarrow 0 \forall t$, to rule out corner solutions $C_t = 0$.
- This implies $\mu_t = 0 \forall t$, thus $\frac{\partial U(\cdot)}{\partial C_t} = \lambda_t$
- Moreover, since we assumed $f(0) = 0$, positive consumption also requires $K_t > 0$ from period $t = 0$ through period $t = T$.
- Thus, $\omega_{t+1} = 0$ for $t = \{0, \dots, T - 1\}$.
- Finally since $U(\cdot)$ is strictly increasing,
 $f(K_t) - C_t - K_{t+1} = 0 \quad \forall t$

- Putting all pieces together, we get following characterization of optimal solution

$$K_{t+1} + C_t = f(K_t) \quad (4)$$

$$\frac{\frac{\partial U(C_0, \dots, C_T)}{\partial C_t}}{\frac{\partial U(C_0, \dots, C_T)}{\partial C_{t+1}}} = f'(K_{t+1}) \quad (5)$$

$$\lambda_T K_{T+1} = 0 \quad (6)$$

- The LHS of (5) is the marginal rate of substitution between two periods and its RHS gives the compensation for an additional unit of saving.

- Since utility is increasing in consumption, $\lambda_T > 0$, and so $K_{T+1} = 0$ (it is optimal to consume everything in the last period).
- The optimal plan is given by

$$K_{t+1} + C_t = f(K_t) \quad (7)$$

$$\frac{\frac{\partial U(C_0, \dots, C_T)}{\partial C_t}}{\frac{\partial U(C_0, \dots, C_T)}{\partial C_{t+1}}} = f'(K_{t+1}) \quad (8)$$

and the two boundary conditions, $K_{T+1} = 0$ and initial level of capital K_0

The deterministic infinite-horizon Ramsey model

- Note that, (8) depends on the entire time profile of consumption (\rightarrow need to solve $2T - 1$ simultaneous equations).
- if $T \rightarrow \infty$, we cannot solve this system.
- To circumvent this problem, we restrict to problems that have a recursive structure (i.e., the problems pose themselves in each period the same way)
- For the Ramsey problem, we need to assume that $U(\cdot)$ takes the form stated in lecture 2 eq(1).

- We continue to assume that $\lim_{C \rightarrow 0} u'(C) = \infty$, so consumption is always positive and we can ignore $C_t \geq 0$
- The Ramsey problem with infinite time horizon

$$\begin{aligned} \max_{\{C_t, K_t, \dots\}} \quad & \sum_{t=0}^{\infty} \beta^t u(C_t) \\ & C_t + K_{t+1} \leq f(K_t) \quad \forall t \\ & 0 \leq K_{t+1} \\ & K_0 \text{ given} \end{aligned}$$

- We can derive the necessary conditions by maximizing the following Lagrangian with respect to $C_0, K_1, C_1, K_2, \dots$

$$\mathcal{L} = \sum_{t=0}^T \beta^t [u(C_t) + \lambda_t(f(K_t) - C_t - K_{t+1}) + \omega_{t+1}K_{t+1}]$$

- In order to keep consumption positive, $K_t > 0$ has to hold for all t until "the end of time".
- Moreover, assuming strictly increasing $u(c_t)$ implies $f(K_{t+1}) = C_{t+1} + K_{t+1}$
- Thus, we have the following FOCs

$$u'(C_t) = \lambda_t \quad (9)$$

$$\lambda_t = \beta \lambda_{t+1} f'(K_{t+1}) + \omega_{t+1} \quad (10)$$

$$f(K_t) = C_t + K_{t+1} \quad (11)$$

$$\lim_{T \rightarrow \infty} \beta^T \lambda_{T+1} K_{T+1} = 0 \quad (12)$$

- Plugging (9) into (10) and (12)

$$u'(C_t) = \beta f'(K_{t+1}) u'(C_{t+1}) \quad (13)$$

$$C_t + K_{t+1} = f(K_t) \quad (14)$$

$$\lim_{T \rightarrow \infty} \beta^T u'(C_T) K_{T+1} = 0 \quad (15)$$

- Eq (13) is referred to the Euler equation for consumption.
- It is equivalent to condition (8) (given the preference specification)
- The flow budget constraint, eq (14) also looks familiar.
- Eq (15) is the so called transversality condition. It is the limit of terminal condition $\lambda_T K_{T+1} = 0$
- It states that the present value of the terminal capital stock must approach zero.

- We can solve C_t from (14) and then plug it into (13) and (15)

$$\frac{u'(f_t(K_t) - K_{t+1})}{u'(f_{t+1}(K_{t+1}) - K_{t+2})} = \beta f'(K_{t+1}) \quad (16)$$

$$\lim_{T \rightarrow \infty} \beta^T u'(f(K_T) - K_{T+1}) K_{T+1} = 0 \quad (17)$$

- We have reduced the system of difference equations into a second order difference equation.
- Transversality condition (17) and the initial level of capital, $K(0)$, give us a unique solution to (16).

Transversality condition

- Solve $u'(C_T)$ from (13) (i.e., express $u(C_T)$ with the help of $u(C_{T-1})$ and $f'(K_T)$) and plug it into (15)

$$0 = \lim_{T \rightarrow \infty} \beta^T u'(C_T) K_{T+1} = \lim_{T \rightarrow \infty} \beta^T \left[\frac{u'(C_{T-1})}{\beta f'(K_T)} \right] K_{T+1}$$

Iterating backwards gives

$$0 = \lim_{T \rightarrow \infty} \beta^T \left[\frac{u'(C_{T-2})}{\beta^2 f'(K_T) f'(K_{T-1})} \right] K_{T+1}$$

$$0 = \lim_{T \rightarrow \infty} \left[\frac{u'(C_0)}{\prod_{i=1}^T f'(K_i)} \right] K_{T+1}$$

- The transversality condition states that the present value K_{T+1} , measured in the relevant units, has to approach zero when $T \rightarrow \infty$.
- If the present value was positive, the consumer would be saving too much. The representative agent could increase her welfare by increasing consumption.

Solving the model

- We have seen that we can characterize the solution with two first order difference equations (or with one second order difference equation) +the transversality condition
- Generally, we can only solve these equations numerically.
- However, sometimes with particular functional forms we can solve the model analytically.
- Moreover, as with the Solow model,we can always solve the steady state analytically.
- It is also possible to analyze transition dynamics graphically (we will postpone this to the week 4)

The steady state

- At a steady state $C_t = C_{t+t}$ and $K_t = K_{t+1}$ for all t .
- Thus,

$$u'(C^*) = \beta f'(K^*) u'(C^*)$$

$$C^* + K^* = f(K^*)$$

or

$$\frac{1}{\beta} = f'(K^*) \tag{18}$$

$$C^* = f(K^*) - K^* \tag{19}$$

An example: a model with an analytical solution

- Assume that the periodic utility function takes a quadratic form

$$u(C_t) = u_1 C_t - \frac{u_2}{2} C_t^2,$$

where $u_1, u_2 > 0$ and that the production function takes a linear form

$$f(K_t) = AK_t, A > 0.$$

- Now (13) and (14) can be written as

$$C_{t+1} = \frac{u_1}{u_2} \left(1 - \frac{1}{\beta A}\right) + \frac{1}{\beta A} C_t \quad (20)$$

$$K_{t+1} = AK_t - C_t \quad (21)$$

- We will use the method of undetermined coefficients.
- Guess that the consumption, C_t , is a linear function of current capital stock K_t

$$C_t = c_1 + c_2 K_t \quad (22)$$

- If this guess is valid, it has to be consistent with (20), (21) and the transversality condition.
- Substituting (22) into (20) gives

$$c_1 + c_2 K_{t+1} = \frac{u_1}{u_2} \left(1 - \frac{1}{\beta A} \right) + \frac{1}{\beta A} (c_1 + c_2 K_t)$$

$$c_1 + c_2 (AK_t - c_1 - c_2 K_t) = \frac{u_1}{u_2} \left(1 - \frac{1}{\beta A} \right) + \frac{1}{\beta A} (c_1 + c_2 K_t)$$

- The last equation holds for arbitrary values of K_t if constant terms on both sides sum to zero

$$0 = c_1 \left(1 - c_2 - \frac{1}{\beta A} \right) - \frac{u_1}{u_2} \left(1 - \frac{1}{\beta A} \right) \quad (23)$$

and if also the coefficients of variable K_t sum to zero

$$0 = c_2 A - c_2^2 - \frac{1}{\beta A} c_2$$
$$c_2 = A - \frac{1}{\beta A} \quad (24)$$

- One can solve c_1 by inserting (24) into (23).

- Next, we can plug our consumption policy into (21)

$$K_{t+1} = \frac{1}{\beta A} K_t - c_1 \quad (25)$$

- If $1/\beta < A$, the capital stock approaches the stationary solution

$$K^* = -\frac{c_1}{1 - \frac{1}{\beta A}} \quad (26)$$

from any given initial value K_0 .

- The consumption converges to

$$C^* = \frac{u_1}{u_2} \quad (27)$$

- Together these imply that also transversality condition (15) holds.

Summary of the simple Ramsey model in discrete time

- The planner's problem is

$$\begin{aligned} \max_{\{c_t, K_0, \dots\}} \quad & \sum_{t=0}^{\infty} \beta^t u(C_t) \\ C_t + K_{t+1} \leq & F(K_t) + (1 - \delta)K_t \quad \forall t \\ 0 \leq & C_t \\ 0 \leq & K_{t+1} \\ K_0 = & \hat{K} \end{aligned}$$

- Assuming $\frac{\partial U(\cdot)}{\partial C_t} \rightarrow \infty$ when $C_t \rightarrow 0 \forall t$, implies that we can "ignore" the constraint $0 \leq C_t$ and $0 \leq K_{t+1}$ as long as we remember to add the transversality condition (TVC)
- Moreover, since $u(\cdot)$ is strictly increasing in c ,

$$C_t + K_{t+1} = F(K_t) + (1 - \delta)K_t \quad \forall t$$

- Thus, we can just solve the following Lagrangian

$$\mathcal{L} = \sum_{t=0}^T \beta^t [u(C_t) + \lambda_t(F(K_t) + (1 - \delta)K_t - C_t - K_{t+1})] \quad (28)$$

- The first order conditions with respect to C_t and K_{t+1}

$$u'(C_t) = \lambda_t$$

$$\lambda_t = \lambda_{t+1}(F'(K_{t+1}) + (1 - \delta))$$

- Moreover, the flow budget constraint

$$C_t + K_{t+1} = F(K_t) + (1 - \delta)K_t$$

and TVC: $\lim_{T \rightarrow \infty} \beta^T u'(C_T) K_{T+1} = 0$ have to hold.

- The solution is a sequence $\{C_t, K_{t+1}\}$ such that

$$u'(C_t) = \beta(F'(K_{t+1}) + (1 - \delta))u'(C_{t+1}) \quad (29)$$

$$C_t + K_{t+1} = F(K_t) + (1 - \delta)K_t \quad (30)$$

for all t , and

$$\lim \beta^T u'(C_T) K_{T+1} = 0, \quad T \rightarrow \infty \quad (31)$$

and $K_0 = \hat{K}$

- NB: we ditched the notation $f(K) \equiv F(K) - (1 - \delta)K$.

Numerical solutions (ref: Heer and Maussner, ch3)

Finite-horizon models

- Solving T period problem, we need to find a sequence of capital such that

$$U'(F(K_t + (1 - \delta)K_t - K_{t+1})) = \beta(F'(K_{t+1}) + (1 - \delta)) \\ * u'(F(K_{t+1} + (1 - \delta)K_{t+1} - K_{t+2}))$$

holds for $t = 0, \dots, T - 1$ and $K_{T+1} = 0$

- For a given capital stock K_0 , this is a system of T unknown variables, K_1, \dots, K_T and T non-linear equations.
- We can use a non-linear equation solver to get a numerical solution.

Non-linear solvers

- Suppose you want to find an \mathbf{x} such that $\mathbf{G}(\mathbf{x}) = \mathbf{0}$.
- A typical structure for non-linear solvers is the following iterative scheme:

$$\mathbf{x}^{s+1} = \mathbf{x}^s + \mu \Delta \mathbf{x}^s, \quad s = 0, 1, \dots$$

- The solvers start with an initial guess of the solution, \mathbf{x}^0 , determine a direction of change, $\Delta \mathbf{x}$, and a step length μ , then proceed to the next guess of the solution, \mathbf{x}^1 .
- This process continues until either $\mathbf{G}(\mathbf{x}^s) \approx \mathbf{0}$ or $\mathbf{x}^{s+1} \approx \mathbf{x}^s$.

- How to choose the initial guess $\mathbf{x}^0 = (K_1^0, K_2^0, \dots, K_T^0)$?
- Need to make sure that consumption stays positive in each period.
- You can try to set K equal to a fraction of $F(K_0) + (1 - \delta)K_0$ for each period.
- The next problem is that the algorithm may end up selecting a point where consumption is negative. If, for example, $u(c) = \ln(c)$, this will result in an error message.
- One solution is to insert a penalty function that hopefully prevents the algorithm from choosing these points.

Infinite-horizon models

- The approach used to solve finite-horizon models can be generalized to infinite-horizon models by taking advantage of the models' property to approach a steady state.
- We just replace $K_{T+1} = 0$ with $K_{T+1} = K^*$.
- Given that there is a stable steady state, the model will converge to that from arbitrary initial conditions.
- practical problems:
 - How to choose T ?
 - How to choose the initial guess, i.e., $(K_1^0, \dots, K_T^0, K^*)$?

How to choose T

- T has to be large enough so that K_{T+1} is close to K^*
- A method for choosing T:
 1. Start with some small T and solve the model.
 2. Then increase T to T' and solve this larger system.
 3. Compare the first T elements of the latter solution to those of the first solution. if the two solutions are close, T is large enough.
 4. Otherwise, increase T and return to step 1.

Choosing the initial value

- The approach used previously does not necessarily work. If K_0 is small relative to K^* , C_T would be negative.
- Another easy solution would be to set $K_t^0 = K^*$ for $t = 1, \dots, T$. However, now it could be that $C_0 < 0$ if K_0 is small enough.
- A method for selecting the initial value:
 1. Choose K'_0 that is close to K^* and use a non-linear solver to get a solution to this problem
 2. Use this solution as a starting value for smaller K'_0
 3. Continue this until K'_0 has reached K_0 .